

Product Manual

1 Product selection table

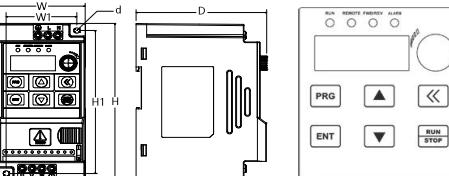
Model	Rated Power(kW)	Input Voltage Range	Rated Output Current(A)
VM600G-2SIR75-E	0.75	AC 220V±15%	4
VM600G-2SIR5-E	1.5		7
VM600G-2SIR2-E	2.2		9.6
VM600G-4TTR75-E	0.75	AC 380V±15%	2.5
VM600G-4TTR5-E	1.5		3.8
VM600G-4TTR2-E	2.2		5.1
VM600G-4T004-E	4		9
VM600G-4TRS5-E	5.5		13
VM600G-4TRS-E	7.5		17

2 Technical specification table

Input frequency range	50/60Hz, fluctuation range±5%
Output voltage range	AC 0~ input voltage
Output frequency range	0~1000Hz
Control mode	V/F
Overload capacity	150% rated current 60s, 180% rated current 1s
Degree of protection	IP20
altitude	Normal use below 1000m, derating 1% for every 100m rise above 1000m, up to 3000m
Ambient temperature	-10°C~+50°C (ambient temperature is 40°C~50°C, please use derating)
humidity	Less than 95%RH, no water droplet condensation
shake	Less than 5.9m/s ² (0.6g)
Storage temperature	-25°C~+60°C

3 Structural Dimensions (mm)

Model	Shape Dimensions			Installation Dimensions		Cuts-outs
	H	W	D	H1	W1	d
VM600G-2SIR75						
VM600G-2SIR5						
VM600G-2SIR2						
VM600G-4TTR75						
VM600G-4TTR5						
VM600G-4TTR2						
VM600G-4T004	196	95	132	179	79	5.5
VM600G-4TRS5	225	115	154	208	99	5.5

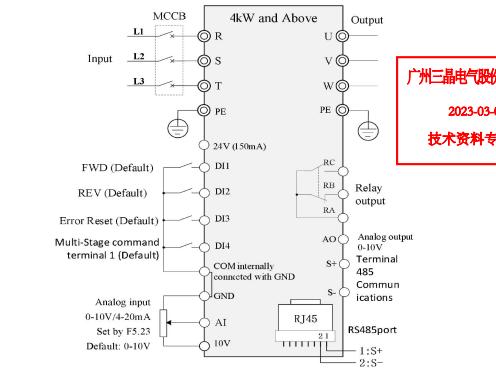
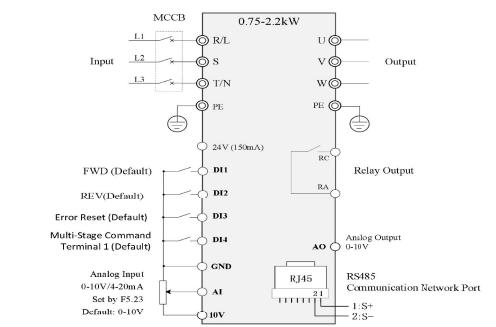


4 Keyboard operation

Category	Name	Function
Indicators	LED indicator	RUN: on/run, off/stop REMOTE: On/Terminal Control, Off/Keypad Control, Flash/Communication Control FWD/REV: On/Forward, Off/Reverse, Flash/Reverse ALARM: flashing/faulty, off/normal
	PRG	Menu entry or exit
Button	ENT	Enter the parameters step by step, save parameter adjustments
	△	Increase parameter or its value
	▽	Decrease parameter or its value
	>>	During parameter setting, select the modification bit of the parameter. During stop/run monitoring, the display parameters can be selected cyclically
		During parameter setting, select the modification bit of the parameter. During stop/run monitoring, the display parameters can be selected cyclically

Category	Name	Function
	RUN/STOP	In keyboard operation mode, control run and stop control It can be used for fault reset in the event of a fault mode alarm
Potentiometer	Speed Adjusting Potentiometer	Can be used for speed (frequency) adjusting

5 Terminal operation



Terminal	Name	Description
R/L, S, T/N	Power input	Connected to input power
U, V, W	Output Power	Connect the motor
(Ground symbol)	Grounding	Connected to ground
10V/GND	10V Power	Maximum output current: 20mA
24V/COM	24V Power	Maximum output current: 150mA
AI/GND	Analog Input	Input: DC 0V ~ 10V or 0~20mA, parameter F5.41 control
AO/GND	Analog Output	0~10V
DI1/DI2 DI3/DI4	Digital Input	External digital signal input
RA/RB/RC	Relay Output	RA/RC is normally open, RA/RB is normally closed
S+/S-	RS485 communication	S+: positive terminal of differential signal, S-: negative terminal of differential signal
RJ45 Port		As shown in the image above: 1 foot is connected to S+ and 2 feet are connected to S-

6 Group F functional parameter table

- Indicates that the setting value of this parameter can be changed when the VFD is in stop or running state;
- Indicates that the setting value of this parameter cannot be changed when the VFD is running;
- ◎ Indicates that the value of this parameter is the actual detection record value and cannot be changed;

Code	Name	Range	Default	Feature	RAM Address
F0.00	Industrial Macro	0: Default Parameter Macro 6: Spring Mechanical Application Macro 8: Woodworking Machinery Macro 9: Tile Press Application Macro 10-12: Guy Custom Macro	0	●	0000
F0.01	Run the command channel	0: Keyboard control 1: Terminal control 2: RS485 communication control	0	●	0001
F0.03	Main Frequency Source X Option	0: Keyboard number given frequency F0.08 1: Keyboard potentiometer given 2: All is given 3: Reserved 4: Terminal UP/DW 5: Reserved 6: Multi-stage speed command 7: Program control (PLC) given terminal 8: PID control given 9: RS485 communication is given	1	●	0003
F0.04	Auxiliary frequency source Y Selection	Same as F0.03	0	●	0004
F0.05	Selection of Y range of auxiliary frequency source during superposition	0: Relative to the maximum frequency F0.10 1: Relative to frequency source X	0	○	0005
F0.06	Y range of auxiliary frequency source in superposition	0%~150%	100%	○	0006
F0.07	Combination mode of main and auxiliary channels	LED bits: Frequency source selection 0: Primary frequency source 1: The result of the main and auxiliary operations 2: Switch between main and auxiliary 3: Switch between the main frequency source and the operation result 4: Switch the auxiliary frequency source and the operation result LED 10 bits: Combination mode selection 0: Primary + Auxiliary 1: Primary - Auxiliary 2: MAX {Primary, Auxiliary} 3: MIN {Primary, Auxiliary} 4: Main × Auxiliary	0	○	0007
F0.08	Keyboard numbers set the frequency	0.00~F0.10	50.00Hz	○	0008
F0.09	Rotation direction selection	0: The direction remains the same 1: The direction is reversed 2: Reverse ban	0	○	0009
F0.10	Maximum frequency	0.00~320.00Hz	50.00Hz	●	000A
F0.11	Upper limit frequency source selection	0: The upper frequency number is given 1: All 2: Reserved 3: Reserved 4: Reserved 5: RS485 communication given 6: Reserved 7: Keyboard potentiometer given	0	●	000B
F0.12	Upper limit frequency digital setting	Lower limit frequency - Maximum output frequency F0.10	50.00Hz	○	000C
F0.14	Lower limit frequency	0.00~Upper limit frequency F0.12	0.00Hz	○	000E
F0.15	Lower limit frequency running mode	0: Runs at the lower limit frequency 1: Stop 2: Zero speed operation	0	○	000F
F0.16	Carrier frequency	0.5~16.0kHz	Model settings	●	0010
F0.17	Carrier PWM wave characteristic selection	Single-digit: PWM mode selection 0: PZV 1: 7 segments: LED ten-bit: The carrier is related to the output frequency 0: Independent of output frequency 1: Related to output frequency LED 10 bits: random PWM depth 0: Closed 1-8: Turn on, adjust the depth LED kilobits: Overmodulation option 0: Off 1: Turn on	1010	●	0011
F0.18	Acceleration time1	0.01~650.00s	Model settings	○	0012
F0.19	Deceleration	0.01~550.00s	Model	○	0013
F0.20	Parameter initialization	0: No action 1: Restore factory value (do not restore motor parameters) 2: Clear the failure record 3: Restore factory value (restore motor parameters)	0	●	0014
F0.21	Function code modifies properties	0: Can be modified 1: Not modifiable	0	○	0015
F0.23	Acceleration and deceleration time unit	0: 1Sec 1: 0.1Sec 2: 0.01Sec	2	●	0017
F0.24	Acceleration and deceleration time reference frequency	0: Maximum frequency F0.10 1: Set the frequency 2: 100Hz	0	●	0018
F0.25	Fan control	Single-bit: start-stop control 0: The fan runs after the inverter is powered on 1: Shutdown is related to temperature, and operation is operation 2: The shutdown fan stops, and the operation is temperature-dependent Ten digits: Enable the speed regulation function 0: Off 1: Turn on	01	○	0019
F0.26	Frequency instruction decimal point	1.1 decimal place 2.2 decimal places	2	●	001A
F1.00	Start-up operation mode	LED bits: start mode 0: Starts by the start frequency 1: DC brake first and then start from the starting frequency 2: Start after speed tracking and direction judgment LED 10 bits: rotational speed tracking direction 0: One to the direction of the shutdown 1: One to the starting direction 2: Automatic search	0	●	0100
F1.02	Speed tracking time	0.01~60.00s	0.50s	○	0102
F1.03	Startup frequency	0.00~60.00Hz	0.00Hz	○	0103
F1.04	Startup frequency duration	0.0~50.0s	0.0s	●	0104
F1.05	Brake current limit	0.0~150.0%	0.0%	●	0105
F1.06	Braking time before starting	0.0~60.0s	0.0s	●	0106
F1.07	Acceleration and deceleration when	0: Straight line 1: S-curve	0	●	0107
F1.08	Source starting acceleration rate	20.0%~100.0%	50.0%	●	0108
F1.09	Source starting deceleration rate	20.0%~100.0%	50.0%	●	0109
F1.10	Shutdown mode	0: Deceleration stops 1: Free shutdown	0	○	010A
F1.11	Step DC braking start frequency	0.00~F0.10	0.00Hz	○	010B
F1.12	Downtime DC braking waiting time	0.0~100.0s	0.0s	○	010D
F1.13	Shutdown DC braking current	0.0~150.0%	0.0%	○	010C
F1.14	Downtime DC braking duration	0.0~100.0s	0.0s	○	010E
F1.15	Brake utilization rate	0% ~ 100%	100%	○	010F
F1.16	Energy consumption, braking action voltage	115.0%~140.0%	125%	●	0110
F1.17	Zero speed holding torque time	0~6000.0sec When set to 6000.0s, it is maintained without time limit	0	●	0111
F1.18	Zero speed holding torque	0~150.0%	Model settings	●	0112
F1.19	The rotational speed tracks the current gain	0~100.00%	10.00%	○	0A1C
F1.20	Speed tracking gain	0~100.00%	5.00%	○	0A1D
F1.21	The rotational speed tracks the current	10~200%	60%	○	0A1E
F2.00	Motor type	0: Asynchronous motor (AM) 1: Permanent magnet synchronous motor (PMSM) 2: Single-phase asynchronous motor (only support V/F control)	0	●	0200
F2.01	Motor power rating	0.4~400.0kW	Model settings	●	0201
F2.02	Motor rated voltage	0~440V	Model settings	●	0202
F2.03	Motor rated	0.1~2000.0A	Model		0203

Code	Name	Range	Default	Feature	RAM Address	Code	Name	Range	Default	Feature	RAM Address	Code	Name	Range	Default	Feature	RAM Address
	current	settings						45: User-defined fault 2 47: Emergency stop 49: Decelerating DC braking 50: The running time is cleared					LED digits: the first set of displays 0: Output frequency 1: Given frequency 2: Bus voltage 3: Output voltage 4: Output current 5: Output power 6: Output torque 7: DI input status 8: DO output status 9: AI voltage A: Reserved				
F2.04	Motor rated frequency	0.01~Maximum frequency	Model settings	●	0204	F5.15	Input terminal filter time	0.000~1.000s	0.010s	○	050F	F6.28	User defined output selection (EX)1	0: Operating frequency 1: Set the frequency 2: Bus voltage 3: Output voltage 4: Output current 5: Output power 6: Output torque 7-8: Reserved 9: AI1 input 10: Reservation	0	○	061C
F2.05	Motor rated speed	0~65000rpm	Model settings	●	0205	F5.16	The terminal controls the operating mode	0: Two-wire system 1 1: Two-wire system 2 2: Three-wire system 1 3: Three-wire system 2	0	●	0510	F6.29	User-selected comparison method 1	Single-digit: Compare test methods 0: equal to (EX == X1) 1: Greater than or equal to 2: Less than or equal to 3: Interval comparison (X1 ≤ EX ≤ X2) 4: Bit test (EX & X1-X2) Ten bits: Output mode 0: False value output 1: Truth output	0	○	061D
F2.06	Motor stator resistance	0.001~65.000	Model settings	●	0206	F5.17	U/D/DW controls the rate of frequency increase and decrease	0.01~655.35Hz/s	0.50Hz/s	○	0511	F6.30	User-defined dead zone 1	0 ~ 65535	0	○	061E
F2.07	Motor rotor resistance	0.001~65.000	Model settings	●	0207	F5.18	All lower limit	0.00V ~ F5.20	0.00V	○	0512	F6.31	User-defined I outputs comparison value of 1	0 ~ 65535	0	○	061F
F2.08	Motor stator and rotor inductance	0.1~6500.0mH	Model settings	●	0208	F5.19	The upper limit of AI corresponds to the setting	-100.0% ~ +100.0%	0.00%	○	0513	F6.32	User-defined I outputs comparison value of 2	0 ~ 65535	0	○	0620
F2.09	Motor stator and rotor mutual inductance	0.1~6500.0mH	Model settings	●	0209	F5.20	All upper limit	F5.18 ~ +100.0V	10.00V	○	0514	F6.33	User-defined output selection (EX)2	Same as F6.28	0	○	0621
F2.10	The motor no-load current	0.1~650.0A	Model settings	●	020A	F5.21	The AI upper limit is set accordingly	-100.0% ~ +100.0%	100.00%	○	0515	F6.34	User-selected comparison method 2	Same as F6.29	0	○	0622
F2.11	Teach-in selection of motor parameters	1: Rotary self-learning 2: Static self-learning	0	●	020B	F5.22	All filter time	0.00~10.00sec	0.10sec	○	0516	F6.35	User-defined dead zone 2	0 ~ 65535	0	○	0623
F2.12	G/P models	0: G-type machine; 1: P-type machine	0	○	020C	F5.23	AI input selection	0: -10V 1: +20mA 2: -20mA 3: +20mA 4: -4.5V	0	○	0517	F6.36	User-defined I outputs comparison value of 1	0 ~ 65535	0	○	0624
F2.13	Single-phase asynchronous motor matching ratio	10~200%	80%	●	020D	F5.24	DII enable delay time	0.0~360.0s	0	○	0521	F6.37	User-defined I outputs comparison value of 2	0 ~ 65535	0	○	0625
F2.14	Single-phase motor current calibration coefficient	50~200%	120%	●	020E	F5.25	DII enable delay time	0.0~360.0s	0	○	0522	F7.06	Speed display factor	0.0001 ~ 6.5000	0.3000	○	0706
F4.00	Linear VF curve selection	0: Straight VF curve; 1: Multipoint V/F curve 2: Square VF curve 3~11: VF curves to the power of 1, 1~19, respectively	0	●	0400	F5.26	DII enable delay time	0.0~360.0s	0	○	0523	F7.07	IGBT temperature	0~100	-	○	0707
F4.01	Manual torque boost	0.1~50.0%, 0 automatic torque boost	Model settings	○	0401	F5.27	DII energy ban delay time	0.0~360.0s	0	○	0524	F7.08	Rectifier bridge temperature	0~100	-	○	0708
F4.02	Torque boost cut-off frequency	0.001Hz ~F0.10	50.00Hz	●	0402	F5.28	The input terminal valid state is set to 1	0: Closure is valid 1: Disconnect is valid LED bits: D11 terminal LED Ten-digit: D12 terminal LED 100 bits: D13 terminal LED thousands: D14 terminal	0000	●	0525	F7.09	Cumulative run time	0~65535h	-	○	0709
F4.03	Self-setting frequency F1	0.00~F4.05	3.00Hz	●	0403	F5.29	The input terminal valid state is set to 1	0: Closure is valid 1: Disconnect is valid LED bits: D11 LED Ten-bit: Reserved LED 100 bits: Reserved	0000	●	0525	F7.10	Product number	-	-	○	070A
F4.04	Self-setting frequency F1	0.0~100.0%	10.0%	●	0404	F5.30	The input terminal valid state is set to 2	0: Closure is valid 1: Disconnect is valid LED bits: AI1 LED Ten-bit: Reserved LED 100 bits: Reserved	0000	●	0526	F7.11	Software version	-	-	○	070B
F4.05	Self-setting frequency F2	F4.03~F4.07	5.00Hz	●	0405	F5.31	The input terminal valid state is set to 1	0: Closure is valid 1: Disconnect is valid LED bits: D11 terminal LED Ten-digit: D12 terminal LED 100 bits: D13 terminal LED thousands: D14 terminal	0000	●	0525	F7.12	reserved	-	-	○	070C
F4.06	Self-setting voltage V2	0.0~100.0%	15.0%	●	0406	F5.32	The input terminal valid state is set to 2	0: Closure is valid 1: Disconnect is valid LED bits: AI1 LED Ten-bit: Reserved LED 100 bits: Reserved	0000	●	0526	F7.13	Cumulative power-up time	0~65535h	-	○	070D
F4.07	Self-setting frequency F3	F4.05~F4.09	8.00Hz	●	0407	F5.33	The input terminal valid state is set to 1	0: Closure is valid 1: Disconnect is valid LED bits: D11 terminal LED Ten-digit: D12 terminal LED 100 bits: D13 terminal LED thousands: D14 terminal	0000	●	0525	F7.14	Cumulative power consumption	-	-	○	070E
F4.08	Self-setting voltage V3	0.0~100.0%	22.0%	●	0408	F5.34	The input terminal valid state is set to 2	0: Closure is valid 1: Disconnect is valid LED bits: AI1 LED Ten-bit: Reserved LED 100 bits: Reserved	0000	●	0526	F7.16	Output power correction factor	0~100.0%	10.0%	○	0A1A
F4.09	Self-setting frequency F4	F4.07~Motor rated frequency F2.04	12.00Hz	●	0408	F5.35	The input terminal valid state is set to 1	0: Closure is valid 1: Disconnect is valid LED bits: AI1 LED Ten-bit: Reserved LED 100 bits: Reserved	0000	●	0525	F7.17	Power display dimension selection	0~Power Display Percentage (%) 1~Power display kilowatt (KW)	0	○	0A1B
F4.10	Self-setting voltage V4	0.0~100.0%	31.0%	●	040A	F5.36	The input terminal valid state is set to 2	0: Closure is valid 1: Disconnect is valid LED bits: AI1 LED Ten-bit: Reserved LED 100 bits: Reserved	0000	●	0526	F8.00	Jog operating frequency setting	0.00~F0.10	2.00Hz	○	0800
F4.11	Oscillation suppression gain	0.0~10.0	5.0	○	041B	F6.02	Relay output 1 selected	0: No output 1: The converter is running 2: Fault output (fail-safe)	2	○	0602	F8.01	Jog acceleration time	0.01~650.0ms	10.00s	○	0801
F4.12	Oscillation suppression filter time	1~1000ms	50ms	○	040C	F6.03	Virtual VDO output selection	0: Invalid 1: Effective	0	●	0606	F8.02	Jog deceleration time	0.01~650.0ms	10.00s	○	0802
F4.13	Magnetic flux braking gain	0~500%	Model settings	○	0A17	F6.04	Virtual VDO output selection	0: Invalid 1: Effective	0	●	0606	F8.03	Acceleration time	0.01~650.0ms	10.00s	○	0803
F4.16	AVR function	0: Invalid 1: Effective	0	○	0410	F6.05	reserved	0: Invalid 1: Valid for terminal commands LED 10 bits: communication control selection 0: Invalid for communication command 1: Valid for communication commands LED 100 bits: reserved LED thousands: reserved	0100	○	0702	F8.04	Deceleration time 2	0.01~650.0ms	10.00s	○	0804
F4.29	EVF torque boosts gain	0~500%	100%	○	0419	F6.06	Virtual VDO output selection	0: Invalid 1: Valid for terminal commands LED 10 bits: communication control selection 0: Invalid for communication command 1: Valid for communication commands LED 100 bits: reserved LED thousands: reserved	0	●	0606	F8.05	Acceleration time 3	0.01~650.0ms	10.00s	○	0805
F4.30	EVF torque increases filter time	1~1000ms	20ms	○	041A	F6.07	Keyboard key STOP key range	0: Invalid for terminal command 1: Valid for terminal commands LED 10 bits: communication control selection 0: Invalid for communication command 1: Valid for communication commands LED 100 bits: reserved LED thousands: reserved	0100	○	0702	F8.06	Deceleration time 4	0.01~650.0ms	10.00s	○	0806
F4.31	EVF torque compensation gain	0~500.0%	0%	○	041B	F6.08	Keyboard operation displays parameter 1	LED digits: the first parameter display 0: Output frequency 1: Given frequency 2: Bus voltage 3: Output voltage 4: Output current 5: Output power 6: Output torque 7: DI input status 8: DO output status 9: AI voltage A: Reserved	3420	○	0703	F8.07	Acceleration time 5	0.01~650.0ms	10.00s	○	0807
F4.32	EVF torque compensation for filter time	1~1000ms	100ms	○	041C	F6.09	Keyboard operation displays parameter 1	LED digits: the first parameter display 0: Output frequency 1: Given frequency 2: Bus voltage 3: Output voltage 4: Output current 5: Output power 6: Output torque 7: DI input status 8: DO output status 9: AI voltage A: Reserved	3420	○	0703	F8.08	Deceleration time 4	0.01~650.0ms	10.00s	○	0808
F5.00	Multi-function input terminal 1 (D11)	0: Not functional 1: Forward Rotation Operation (FWD) 2: Reverse Run (REV)	1	●	0500	F6.10	Keyboard operation displays parameter 1	LED digits: the first parameter display 0: Output frequency 1: Given frequency 2: Bus voltage 3: Output voltage 4: Output current 5: Output power 6: Output torque 7: DI input status 8: DO output status 9: AI voltage A: Reserved	3420	○	0703	F8.09	Emergency stop deactivation time	0.01~650.0ms	10.00s	○	0809
F5.01	Multi-functional input Terminal 2 (D12)	3: Threewire operation control 4: Reverse Rotation Jog (RJOG) 5: Reverse Jogs (RJOG)	2	●	0501	F6.11	Keyboard operation displays parameter 1	LED digits: the first parameter display 0: Output frequency 1: Given frequency 2: Bus voltage 3: Output voltage 4: Output current 5: Output power 6: Output torque 7: DI input status 8: DO output status 9: AI voltage A: Reserved	3420	○	0703	F8.10	Hopping frequency	0.00~F0.10	0.00Hz	○	080A
F5.02	Multi-functional Input Terminal 3 (D13)	6: Terminal UP 7: Terminal DOWN 8: Free parking	9	●	0502	F6.12	AO1 output selection	0: Invalid 1: Reserved 10: reserved 11: reserved 12: Communication settings 13: Motor direction 14: Output current (0~1000A, corresponding to 0~10V) 15: Output voltage (0~1000V, corresponding to 0~10V) 16: Bus voltage (0~1000V, corresponding to 0~10V)	0	○	060C	F8.11	Reverse dead time	0~120.0s	0.0s	○	080B
F5.03	Multi-functional input terminal 4 (D14)	9: The fan is paused 10: External fault normally open input 11: External fault stage speed command terminal 12: Multi-stage speed command terminal	12	●	0503	F6.13	Reserved	0: Invalid 1: Reserved 10: reserved 11: reserved	0	○	060D	F8.12	The arrival time of this run	0~65000min	0min	○	080D
F5.04	All is used as DI terminal function selection	13: Multi-stage speed command terminal 14: Multi-stage speed command terminal 15: Multi-stage speed command terminal 16: Select terminal 1 for acceleration and deceleration time 17: Select terminal 2 for acceleration and deceleration time 18: Frequency source switching 19: UP/DOWN setting is cleared 20: Run command to switch terminals 21: Acceleration and deceleration prohibited 22: PID paused 23: PLC status reset 30: Reserved 31: Reserved 32: Immediate DC braking 33: PID action direction is reversed 34: External parking terminal 1 35: Control command toggle terminal 36: PID parameter switching terminal 44: User-defined fault 1	0	●	0504	F6.14	Relay 1 outputs the delay time	0~360.0s	0	○	0614	F8.13	The time reaches the action selection	0: Continue running 1: Fault prompt	0	○	080E
F5.10	Virtual VDI terminal function selection	24: PID paused 25: PLC status reset 30: Reserved 31: Reserved 32: Immediate DC braking 33: PID action direction is reversed 34: External parking terminal 1 35: Control command toggle terminal 36: PID parameter switching terminal 44: User-defined fault 1	0	●	050A	F6.15	Relay 1 disconnects the delay time	0~360.0s	0	○	0616	F8.14	Terminal tapping is preferred	1: Invalid 2: Effective	1	○	080F
						F6.16	Relay 1 disconnects delay	0~360.0s	1.00	●	0610	F8.15	PID AI feedback toggles the limit	0.0~F8.18	45.0%	○	0811
						F6.17	VDO disconnects delay time	0~360.0s	0	○	061A	F8.16	PID AI feedback toggles the limit	F8.17~100.0%	55.0%	○	0812
						F6.18	Relay output active level	0: Positive logic 1: Inverse logic Digits: Y Ten: RL1 Hundreds: RL2 Thousands: vY1	0	○	061B	F8.17	The carrier frequency is adjusted with temperature	0: Temperature independent 1: Temperature dependent, -75, 1.0Khz	1	○	0813
						F6.19	Relay output active level	0: Positive logic 1: Inverse logic Digits: Y Ten: RL1 Hundreds: RL2 Thousands: vY1	0	○	061B	F8.18	Set the cumulative power-on time arrival time	0h ~ 65000h	0h	○	0814
						F6.20	Relay output active level	0: Positive logic 1: Inverse logic Digits: Y Ten: RL1 Hundreds: RL2 Thousands: vY1	0	○	061B	F8.19	Set the cumulative run arrival time	0h ~ 65000h	65000h	○	0815
						F6.21	Relay output active level	0: Positive logic 1: Inverse logic Digits: Y Ten: RL1 Hundreds: RL2 Thousands: vY1	0	○	061B	F8.20	Set the cumulative time to reach action	0: Continue running 1: Fault prompt	0	●	0816

Code	Name	Range	Default	Feature	RAM Address
F8.23	Set the cumulative power-on time to reach the action	6: Continue running 1: Fault prompt	0	•	0817
F9.00	The PID controller gives the signal source	0: Keyboard number PID given 1: Keyboard potentiometer given 2: AI1 3: reserved 4: reserved 5: RS485 communication given 6: Multi-stage speed is given	0	○	0900
F9.01	Keyboard number PID given	0.00~100.0%	50.0%	○	0901
F9.02	PID controller feedback signal source	0: Keyboard numeric PID feedback 1: Keyboard potentiometer feedback 2: AI1 3: reserved 4: reserved 5: reserved 6: RS485 communication feedback	2	○	0902
F9.03	PID control selection	LED single bits: feedback feature selection 0: positive characteristic 1: negative characteristic LED 10 bits: PID adjustment direction selection 0: Reverse ban 1: Reverse allow LED 100 bits: alignment selection 0: Non-center alignment 1: Center alignment LED thousands: reserved	0100	○	0903
F9.04	The maximum range of the feedback signal	0~100.0	100.0	○	0904
F9.05	Proportional deviation limit	0.00~100.00	1.00	○	0905
F9.06	Integration time 1	0.00~10.00s	0.10s	○	0906
F9.07	Differential gain D	0.00~10.00s	0.00s	○	0907
F9.08	Invert the output frequency	0.0~F0.10	0.00Hz	○	0908
F9.09	PID control deviation limit	0.0~100.0%	0.0%	○	0909
F9.10	Differential limiting	0.00~100.00%	0.10%	○	090A
F9.11	PID set change limit	0.00~100.00s	0.00s	○	090B
F9.12	PID feedback filtering time	0.00~60.00s	0.00s	○	090C
F9.13	PID output filter time	0.00~60.00s	0.00s	○	090D
F9.14	Proportional gain P	0.00~100.00	1.00	○	090E
F9.15	Integration time I2	0.00~10.00s	0.10s	○	090F
F9.16	Differential gain D2	0.00~10.00s	0.00s	○	0910
F9.17	Parameter switching conditions	0: Do not switch 1: Terminal switching 2: Automatic switching according to deviation	0	○	0911
F9.18	Toggle deviation 1	0.0~F9.19	20.0%	○	0912
F9.19	Toggle deviation 2	F9.18~100.0%	80.0%	○	0913
F9.20	PID preset outputs	0.0~100.0%	0.0%	○	0914
F9.21	PID preset output run time	0.0~6500.0s	0.0s	○	0915
F9.22	Parameter minimum of two output deviations	0.00~100.00%	1.00%	○	0916
F9.23	Double output deviation reverse maximum	0.00~100.00%	1.00%	○	0917
F9.24	Integral attributes	Single-digit: integral separation 0: Invalid 1: Effective Ten bits: Output to the limit, whether to stop integration 0: Continue points 1: Stop Credits	0	○	0918
F9.25	Lower limit value of disconnection alarm	0.0~100.0%	0.0%	○	0919
F9.26	Feedback break detection time	0.0~120.0s	0.0s	○	091A
F9.27	Feedback disconnection action selection	0: Continue PID operation without reporting faults 1: Stop and report fault (manual reset) 2: Continue PID operation and output alarm signal 3: Run at the current frequency to output alarm signal 4: Stop and report fault (automatic reset)	0	○	091B
F9.28	PID function selection	0: Normal PID 1: Hibernate PID	0	○	091C
F9.29	Sleep threshold	0.0%~100.0%	60.0%	○	091D
F9.30	Sleep delay	0.0~3600.0s	3.0s	○	091E

Code	Name	Range	Default	Feature	RAM Address
F9.31	Wake-up threshold	0.0%~100.0%	20.0%	○	091F
F9.32	Wake-up delay	0~3600.0s	3.0s	○	0920
F9.33	Minimum output	0.F014 (lower frequency) 1.0Hz	0	●	0921
F9.36	Voltage break alarm upper limit	0.0~100.0%	100%	○	0924
F9.37	PID broken wire detection options	0: Downtime is not detected 1: Shutdown detection	0	○	0925
FA.00	Motor overload protection options	0: Off 1: Turn on	1	○	0A00
FA.01	Motor overload protection factor	0.0~250.0%	100.0%	○	0A01
FA.02	Motor overload working coefficient	20.0~250.0%	80.0%	○	0A02
FA.03	Frequency limits	0.001Hz~99.99Hz	0.00Hz	○	0A03
FA.04	Overvoltage stall gain	0~500%	100%	○	0A04
FA.05	Overvoltage stall point	110%~150%	135%	○	0A05
FA.06	Overvoltage stall filtering time	1~1000ms	5ms	○	0A06
FA.07	Overload rate gain	0~500%	20%	○	0A07
FA.08	Overvoltage speed point	100%~200%	150%	○	0A08
FA.09	Overvoltage rate filtering time	1~1000ms	20ms	○	0A09
FA.10	reserved			○	0A0A
FA.11	Input phase loss protection	0: Off 1: Turn on	1	○	0A0B
FA.12	Output phase loss protection	0: Off 1: Turn on	1	○	0A0C
FA.13	Phase loss protection software detection level	0.0~999.9%	15.0%	○	0A0D
FA.14	PWM parameter settings	Single-digit: Turn on voltage prediction compensation Ten: 0:SSSU, 1:DSDU Hundred-bit: random carrier mode 0: Random carrier 1: Random 0 vector	0000	●	0A0E
FA.15	Hardware current and voltage protection	Single-bit: Hardware Current Limit (CBC) 0: Off 1: On Ten: Hardware overvoltage protection 0: Off 1: On Hundred-bit: SC filter time 1~F Thousands: OC filter time 1~F	1110	○	0A0F
FA.16	CBC Protected Point	100~220%	180%	○	0A10
FA.17	CBC overload protection time	1~5000ms	500ms	○	0A11
FA.18	Busbar undervoltage protection points	40.0% ~ 100.0%	100%	○	0A12
FA.19	Software overvoltage protection point	200.0V ~ 800.0V	Model settings	○	0A13
FA.20	Number of times of self-recovery	0~5	0	○	0A14
FA.21	Interval between fault self-recovery	0.1~100.0s	1.0s	○	0A15
FC.00	485 mailing address	1~247	1	○	0C00
FC.01	communication baud rate selection	0: 300 bps 1: 600 bps 2: 1200 bps 3: 2400 bps 4: 4800 bps 5: 9600 bps 6: 19200 bps 7: 38400 bps 8: 57600 bps 9: 115200 bps	5	○	0C01
FC.02	Modbus data format	0: (8,N,2)8 bits, no checksum, 2 stop bits 1:(8,E,1)8-bit, even-checked, 1-bit stop bit 1:(8,O,1)8-bit, odd, 1-bit stop bit 2:(8,N,1)8 bits, no checksum, 1 stop bit	3	○	0C02
FC.03	Medium communication response delay	0~20ms	2ms	○	0C03
FC.04	Timeout duration of Modbus communication	0.0 (invalid), 0.1s~60.0s	0s	○	0C04
FD.00	Multi-stage speed 0	-100%~100.0%	0	○	0D00
FD.01	Multi-stage speed 1	-100%~100.0%	0	○	0D01
FD.02	Multi-stage speed 2	-100%~100.0%	0	○	0D02
FD.03	Multi-stage speed 3	-100%~100.0%	0	○	0D03
FD.04	Multistage speed 4	-100%~100.0%	0	○	0D04
FD.05	Multistage speed 5	-100%~100.0%	0	○	0D05
FD.06	Multistage speed 6	-100%~100.0%	0	○	0D06
FD.07	Multistage speed 7	-100%~100.0%	0	○	0D07
FD.08	Multistage speed 8	-100%~100.0%	0	○	0D08
FD.09	Multistage speed 9	-100%~100.0%	0	○	0D09
FD.10	Multistage speed 10	-100%~100.0%	0	○	0D0A
FD.11	Multistage speed 11	-100%~100.0%	0	○	0D0B
FD.12	Multistage speed 12	-100%~100.0%	0	○	0D0C
FD.13	Multistage speed 13	-100%~100.0%	0	○	0D0D
FD.14	Multistage speed 14	-100%~100.0%	0	○	0D0E
FD.15	Multistage speed 15	-100%~100.0%	0	○	0D0F
FD.16	PLC operation mode	0: Stop at the end of a single run 1: The final value is maintained at the end of a single run 2: Keep looping	0	○	0D10
FD.17	PLC power-down memory selection	Bit: 0: Power down does not remember 1: Power-down memory Ten: 0: No memory of downtime 1: Shutdown memory PLC stage 2: Shutdown memory PLC stage and running time	00	○	0D11
FD.18	PLC segment 0 running time	0.0s(h) ~ 6553.5s(h)	0.0s(h)	○	0D12
FD.19	PLC segment 0 acceleration and deceleration time selection	0 ~ 3	0	○	0D13
FD.20	PLC segment 1 operating time	0.0s(h) ~ 6553.5s(h)	0.0s(h)	○	0D14
FD.21	PLC section 1 acceleration and deceleration time selection	0 ~ 3	0	○	0D15
FD.22	PLC segment 2 operating time	0.0s(h) ~ 6553.5s(h)	0.0s(h)	○	0D16
FD.23	PLC segment 2 acceleration and deceleration time selection	0 ~ 3	0	○	0D17
FD.24	PLC segment 3 operating time	0.0s(h) ~ 6553.5s(h)	0.0s(h)	○	0D18
FD.25	PLC section 3 acceleration and deceleration time selection	0 ~ 3	0	○	0D19
FD.26	PLC segment 4 operating time	0.0s(h) ~ 6553.5s(h)	0.0s(h)	○	0D1A
FD.27	PLC segment 4 acceleration and deceleration time selection	0 ~ 3	0	○	0D1B
FD.28	PLC segment 5 operating time	0.0s(h) ~ 6553.5s(h)	0.0s(h)	○	0D1C
FD.29	PLC section 5 acceleration and deceleration time selection	0 ~ 3	0	○	0D1D
FD.30	PLC segment 6 uptime	0.0s(h) ~ 6553.5s(h)	0.0s(h)	○	0D1E
FD.31	PLC section 6 acceleration and deceleration time selection	0 ~ 3	0	○	0D1F
FD.32	PLC segment 7 uptime	0.0s(h) ~ 6553.5s(h)	0.0s(h)	○	0D20
FD.33	PLC section 7 acceleration and deceleration time selection	0 ~ 3	0	○	0D21
FD.34	PLC segment 8 operating time	0.0s(h) ~ 6553.5s(h)	0.0s(h)	○	0D22
FD.35	PLC section 8 acceleration and deceleration time selection	0 ~ 3	0	○	0D23
FD.36	PLC segment 9 operating time	0.0s(h) ~ 6553.5s(h)	0.0s(h)	○	0D24
FD.37	PLC section 9 acceleration and deceleration time selection	0 ~ 3	0	○	0D25
FD.38	PLC segment 10 operating time	0.0s(h) ~ 6553.5s(h)	0.0s(h)	○	0D26
FD.39	PLC segment 10 acceleration and deceleration time selection	0 ~ 3	0	○	0D27
FE.00	User password	0 ~ 65535		○	0E00
FE.01	Parameter and key lock selection	0: Do not lock 1: Reserve parameter lock 2: Function parameters and key lock (except RUN/STOP/JOG) 3: All functional parameters and buttons are locked	0	○	0E01

7 Group D monitors the parameter group

Function code	Name	Minimum unit	Change	Mailing address
D0 Group Monitors the parameter group				
D0.00	Operating frequency (Hz)	0.01Hz	●	D000
D0.01	Set frequency (Hz)	0.01Hz	●	D001
D0.02	Bus Voltage(V)	0.1V	●	D002
D0.03	Output Voltage(V)	1V	●	D003
D0.04	Output Current(A)	0.01A	●	D004
D0.05	Output power(kW)	0.1kW	●	D005
D0.06	Output torque (%)	0.1%	●	D006
D0.07	DI input status	1	●	D007
D0.08	DO output status	1	●	D008
D0.09	AI1 voltage (V)	0.01V	●	D009
D0.10	Reserved	-	●	D00A
D0.11	Reserved	-	●	D00B
D0.12	Module temperature	°C	●	D00C
D0.13	Count value	1	●	D00D
D0.14	Lead speed display	1	●	D00E
D0.15	PID setting	1	●	D00F
D0.16	PID feedback	1	●	D010
D0.17	PLC stage	1	●	D011
D0.18	Reserved	1	●	D012
D0.19	Feedback speed (unit: 0.1Hz)	0.1Hz	●	D013
D0.20	Reserved	-	●	D014
D0.21	Reserved	-	●	D015
D0.22	Reserved	-	●	D016
D0.23	Reserved	-	●	D017
D0.24	Reserved	-	●	D018
D0.25	Current power-on time	1Min	●	D019
D0.26	Current running time	0.1Min	●	D01A
D0.27	Reserved	-	●	D01B
D0.28	Communication Settings	0.01%	●	D01C
D0.29	Reserved	-	●	D01D

Function code	Name	Minimum unit	Change	Mailing address
D0 Group Monitors the parameter group				
D0.30	Master frequency X display	0.01Hz	●	D01E
D0.31	Secondary frequency Y display	0.01Hz	●	D01F

8 Group E Failure Logging Group

Parameter	Name	Set the scope and description	Attribute	Mailing address
E0.00	The type of most recent failure	Trouble-free: 0 Accelerated overcurrent: Err01 Deceleration overcurrent: Err02 Constant speed overcurrent: Err03 Accelerated overvoltage: Err04 Deceleration overvoltage: Err05 Constant speed overvoltage: Err06 External fault: Err07 Undervoltage fault: Err09 Inverter overload: Err10 Motor overload: Err11 Overheating: Err13 Modbus overheating: Err14 External fault: Err15 Current detection fault: Err18 Parameter read and write exception: Err21 EEPROM read and write failure: Err22 Cumulative run time reached: Err26 PID 反馈桥接故障: Err31	●	E000
E0.01	Frequency at the time of the most recent fault	0.0Hz—Maximum frequency	●	E001
E0.02	Current at the time of the most recent fault	0.00—655.35	●	E002
E0.03	Bus voltage at the time of the most recent fault	0—810V	●	E003
E0.04	Enter the terminal status at the time of the most recent fault	0—15	●	E004
E0.05	Inverter temperature at the time of the most recent failure	0—65553	●	E005
E0.06	Faulty module temperature	0—100°C	●	E006
E0.07	Fault inverter status	LED bits: Running direction to Forward 1 Reverse LED digitbit: operating status 0: Downtime 1: Standby speed 2: Acceleration 3: Deceleration LED 100 bits: reserved LED thousands: reserved	●	E007
E0.08	Fault run time (from this power-up)	0—65535H	●	E008
E0.09	Fault run time (from total run time)	0—65535H	●	E009
E0.10	Fault output voltage	0—1500V	●	E00A
E0.11	Reserved		●	E00B
Groups E1—E4 are recorded with groups E0				

9 Main fault codes and handling

Fault code	Failure type	The cause of the failure	countermeasure
Err02 Err03 Err04	Accelerates overcurrent Decelerate overcurrent Constant speed overcurrent	The acceleration/deceleration time setting is too short	Extended acceleration/deceleration time
		The selection of frequency converters is too small	Select a frequency converter that matches the motor power and load situation
		There is a ground or short circuit in the output loop of the inverter	Troubleshoot peripheral faults and check whether a short circuit has occurred on the motor end
Err05 Err06 Err07	Accelerated overvoltage Decelerate overvoltage Constant speed overvoltage	The input voltage is on the high side	Adjust the input voltage to the normal range
		The deceleration time is too short	Increase the deceleration time

Fault code	Failure type	The cause of the failure	countermeasure
Err09	Undervoltage fault	The power supply input voltage is too low	Adjust the input voltage to the normal range
Err10	The frequency converter is overloaded	The load is too large or the motor is stalled	Reduce load and check motor and mechanical condition
		The selection of frequency converters is too small	Select a frequency converter with a large power gear
Err11	The motor is overloaded	The motor overload protection parameters are not set appropriately	Reset the parameters
		The load is too large or the motor is stalled	Reduce load and check motor and mechanical condition
Err13	The output is out of phase	Motor failure	Check whether the motor windings are open
		There is an abnormality in the load from the frequency converter to the motor	Troubleshoot the parameter
		The three-phase output of the inverter is unbalanced when the motor is running	Check whether the three-phase winding of the motor is normal and troubleshoot
		The IGBT module is abnormal	Seek technical support
Err14	The module is overheating	The ambient temperature is too high	Improve ambient temperature
		The air duct is blocked	Clean the air duct
		The fan is abnormal	Replace the fan
		The thermistor, inverter module is damaged	Seek technical support
Err15	Peripheral failure	DI signal triggering for external fault	Troubleshoot external signals
Err16	Communication failure	The host computer works abnormally	Check the wiring of the host computer
		RS485 communication line is abnormal	Check the communication cable
		The communication parameter FC group is set incorrectly	Set the communication parameters correctly
Err18	Current detection fault	The circuit self-test failed	Seek technical support
Err21	Data overflow	The control board is abnormal	Seek technical support
Err22	EEPROM read and write failures	The EEPROM chip is damaged	Seek technical support

10 RS485 communication register

Function description	Address	Parameter description	Data description	Attribute
Communication settings	1000H	-10000—10000(number of signs)	Corresponds to maximum frequency=100.00%	Readable and writable
Control commands	2000H	0001: Forward run	-	Write only
		0002: Reverse the run	-	Write only
		0003: Forward jogging	-	Write only
		0004: Reverse jogging	-	Write only
		0005: Free downtime	-	Write only
		0006: Deceleration stops	-	Write only
		0007: Fault reset	-	Write only
Running status	3000H	0001: Forward running	-	read only

Function description	Address	Parameter description	Data description	Attribute
		0002: Reverse running	-	read only
		0003: stoppage	-	read only
Status data monitoring	1001H	Operating frequency (Hz)	2 decimal places	read only
	1002H	Set frequency (Hz)	2 decimal places	read only
	1003H	Bus Voltage(V)	1 decimal place	read only
	1004H	Output Voltage(V)	1 decimal place	read only
	1005H	Output Current(A)	2 decimal places	read only
	1006H	Inverter temperature	1 decimal place	read only
	1008H	Digital input status	DH—DH4 are added by binary bit weights	read only
	100CH	Keyboard potentiometer voltage (V)	1 decimal place	read only
	100AH	AI Voltage(V)	1 decimal place	read only
	1000FH	Load speed display	1 decimal place	read only
Fault status monitoring	1012H	PLC stage	The number of segments in which the PLC is running	read only
	0000: Trouble-free		-	read only
	0002: Accelerates overcurrent		-	read only
	0003: Decelerate overcurrent		-	read only
	0004: Constant speed overcurrent		-	read only
	0005: Accelerated overvoltage		-	read only
	0006: Decelerate overvoltage		-	read only
	0007: Constant speed overvoltage		-	read only
	0009: Undervoltage fault		-	read only
	000A: The frequency converter is overloaded		-	read only
	000B: The motor is overloaded		-	read only
	000D: The output is out of phase		-	read only
	000E: The module is overheating		-	read only
	000F: External failure		-	read only
Communication fault feedback	0012: Current detection fault		-	read only
	0015: Parameter read and write exceptions		-	read only
	0000: Trouble-free		-	read only
	0001: Command code error		-	read only
8000H	0002: Communication transmission error		-	read only
	0003: CRC check error		-	read only
	0004: Invalid address		-	read only
8001H	0005: Invalid data		-	read only
	0006: Invalid parameter changes		-	read only
	0007: The system is locked		-	read only
	0008: Parameters are being stored		-	read only

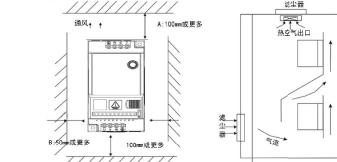
Function description	Address	Parameter description	Data description	Attribute
		0004: Invalid address	-	read only
		0005: Invalid data	-	read only
		0006: Invalid parameter changes	-	read only
		0007: The system is locked	-	read only
		0008: Parameters are being stored	-	read only

11 Description of correspondence address

The communication address listed in the function code table is the write RAM mode, the data is not saved after the inverter is powered off, in the communication, for the write command "06H", if the parameter needs to be powered down and stored, the way of writing EEPROM should be used, the original RAM address highest bit "0" changed to "F", converted into the corresponding EEPROM address, such as: "0XXX" changed to "FXXX", address conversion example:

The upper frequency is F012, the communication address of the write RAM is: 000C, and the address corresponding to EEPROM is: F00C.

Acceleration time F018, the address of the write RAM is 0012, and the address corresponding to EEPROM is: F012. It should be noted that the erasing and writing life of EEPROM is about 1 million times, after exceeding the number of erasing and writing, it will affect the reliability of data storage, if it is not necessary, it is recommended to use write RAM to control communication.

12 Attention to the product installation**13 Scan the code to obtain the electronic file manual:**